

Quiz #3. Physical Mechanics, 2000
Total 9 points.

Answers

1. (3 points) Determine which of the following is scalar and which is vector?

Gradient of a scalar field (∇f) is a _____ Vector _____

Divergence of a flow (velocity) field $\nabla \cdot \vec{V}$ is a _____ Scalar _____

Vorticity $\nabla \times \vec{V}$ is a _____ Vector _____

2. (3 points) For a particle undergoing a uniform circular motion, the position vector of the particle is $\vec{r} = \hat{i} r \cos(\omega t) + \hat{j} r \sin(\omega t)$. Here r is the radius of the circle and ω the angular velocity, both are constant.

- a. Find the velocity (vector) for the particle at time t .

$$\vec{V} = \frac{d\vec{r}}{dt} = -\hat{i} \omega r \sin(\omega t) + \hat{j} \omega r \cos(\omega t)$$

- b. Show (from their definitions) that the velocity is always perpendicular to the position vector.

When $\vec{V} \cdot \vec{r} = 0$, $\vec{V} \perp \vec{r}$.

$$\begin{aligned} \vec{V} \cdot \vec{r} &= \vec{V} \cdot [\hat{i} r \cos(\omega t) + \hat{j} r \sin(\omega t)] \\ &= [-\omega r \sin(\omega t) r \cos(\omega t) + \omega r \cos(\omega t) r \sin(\omega t)] = 0 \end{aligned}$$

Therefore $\vec{V} \perp \vec{r}$.

- c. What does it say about the direction of motion of this particle? Use diagram if you want.

The particle moves along a circle of radius r , and direction is tangential to the circle.

3. (3 points) If force \vec{F} can be written in terms the gradient of scalar f , i.e.,

$$\vec{F} = \nabla f$$

show (yes, prove) that the work done by this force along any closed path is always zero, i.e., $W = \oint \vec{F} \cdot d\vec{r} = 0$. (Hint: First find the work done by this force along a path starting at P_1 and ending at P_2 , then show that if P_1 and P_2 are the same point, i.e., if

the path is closed, the work is zero. You may need to use the definition of total differential $d\mathbf{f} = \frac{\partial \mathbf{f}}{\partial x} dx + \frac{\partial \mathbf{f}}{\partial y} dy + \frac{\partial \mathbf{f}}{\partial z} dz$).

Since

$$\vec{F} = \nabla \mathbf{f} = \hat{i} \frac{\partial \mathbf{f}}{\partial x} + \hat{j} \frac{\partial \mathbf{f}}{\partial y} + \hat{k} \frac{\partial \mathbf{f}}{\partial z} \quad \text{and} \quad d\vec{r} = \hat{i} dx + \hat{j} dy + \hat{k} dz$$

$$\vec{F} \cdot d\vec{r} = \frac{\partial \mathbf{f}}{\partial x} dx + \frac{\partial \mathbf{f}}{\partial y} dy + \frac{\partial \mathbf{f}}{\partial z} dz = d\mathbf{f} \rightarrow$$

$$W = \oint \vec{F} \cdot d\vec{r} = \oint d\mathbf{f} = 0.$$

Or use the Stokes Theorem:

$$W = \oint \vec{F} \cdot d\vec{r} = \iint (\nabla \times \vec{F}) \cdot \vec{n} ds = \iint (\nabla \times \nabla \mathbf{f}) \cdot \vec{n} ds \quad \text{because}$$

$$\nabla \times \nabla \mathbf{f} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \mathbf{f}}{\partial x} & \frac{\partial \mathbf{f}}{\partial y} & \frac{\partial \mathbf{f}}{\partial z} \end{vmatrix} = \hat{i}(\mathbf{f}_{zy} - \mathbf{f}_{yz}) - \hat{j}(\mathbf{f}_{zx} - \mathbf{f}_{xz}) + \hat{k}(\mathbf{f}_{xy} - \mathbf{f}_{yx}) = 0$$